

# Introduction

Goal : For a given function  $f$  in some class of functions, approximate

$$\int \pi(dx) f(x)$$

where the target distribution  $\pi$  is known up a multiplicative constant:  
 $\pi(x) = C\tilde{\pi}(x)$  where  $x \mapsto \tilde{\pi}(x)$  is known

- We use a **Markov chain**  $(X_n)_{n \in \mathbb{N}}$  such that

$$\frac{1}{n} \sum_{i=0}^{n-1} f(X_i) \approx \int \pi(dx) f(x), \quad n \text{ large},$$

- **Theory of Markov chains**: General definitions, invariant measures, ergodicity, Law of Large Numbers, geometric ergodicity, Central Limit theorems. **3 weeks.**
- **Practise of Markov chains**: Metropolis-Hastings Markov chains and variants Pseudo marginal methods, Hamiltonian MCMC. Alternative methods (Sequential MC, Variational Inference, ABC). **3 weeks.**

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# Outline

- ① Activities
- ② Markov chains and Markov kernels
- ③ Finite dimensional laws
- ④ The canonical space
- ⑤ The Markov property

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# Definitions

Let  $(X, \mathcal{X})$  be a measurable space.

## Definition (of a Markov kernel)

We say that  $P : X \times \mathcal{X} \rightarrow \mathbb{R}^+$  is a **Markov kernel**, if for all  $(x, A) \in X \times \mathcal{X}$ ,

- $y \mapsto P(y, A)$  is  $\mathcal{X}/\mathcal{B}(\mathbb{R}^+)$  **measurable**,
  - $B \mapsto P(x, B)$  is a **probability measure** on  $(X, \mathcal{X})$ .
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- In particular,  $P(x, X) = 1$  for all  $x \in X$ .
  - Recall if  $\nu$  is a measure on  $(X, \mathcal{X})$ ,  $A \mapsto \nu(A)$  is well-defined and we can define the integral associated to  $\nu$  and we use the notation  $\nu(f) = \int f(x)\nu(dx)$ ,
  - Since  $P(x, \cdot)$  is a measure, we also use the infinitesimal notation:  $P(x, dy)$ . For example,

$$P(x, A) = \int_X \mathbf{1}_A(y)P(x, dy) = \int_A P(x, dy) .$$



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Let  $\{X_k : k \in \mathbb{N}\}$  be a sequence of random variables on  $(\Omega, \mathcal{G}, \mathbb{P})$  and taking values on  $X$ .

### Definition (of a Markov chain)

We say that  $\{X_k : k \in \mathbb{N}\}$  is a **Markov chain** with Markov kernel  $P$  and initial distribution  $\nu \in M_1(X)$  if and only if

- 1 for all  $(k, A) \in \mathbb{N} \times \mathcal{X}$ ,  $\mathbb{P}(X_{k+1} \in A | X_{0:k}) = P(X_k, A)$ ,  $\mathbb{P}$ -a.s.
- 2  $\mathbb{P}(X_0 \in A) = \nu(A)$ .

# Additional notation

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For all  $\mu \in \mathbb{M}_+(\mathbb{X})$ , all Markov kernels  $P, Q$  on  $\mathbb{X} \times \mathcal{X}$ , and all measurable non-negative or bounded functions  $h$  on  $\mathbb{X}$ ,

- 1  $\mu P$  is the (positive) measure:  
 $A \mapsto \mu P(A) = \int \mu(dx) P(x, A),$
- 2  $PQ$  is the Markov kernel:  $(x, A) \mapsto \int_{\mathbb{X}} P(x, dy) Q(y, A),$
- 3  $Ph$  is the measurable function  $x \mapsto \int_{\mathbb{X}} P(x, dy) h(y).$

- Example

$$\begin{aligned} \mu(P(Qh)) &= (\mu P)(Qh) = (\mu(PQ))h = \mu((PQ)h) \\ &= \int \cdots \int_{\mathbb{X}^3} \mu(dx) P(x, dy) Q(y, dz) h(z) = \mu P Q h \end{aligned}$$

- Iterates of a kernel
  - define  $P^0 = I$  where  $I$  is the identity kernel:  $(x, A) \mapsto \mathbf{1}_A(x)$
  - set for  $k \geq 0$ ,  $P^{k+1} = P^k P.$

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# Finite dimensional law

Let  $\{X_k : k \in \mathbb{N}\}$  be a Markov chain with Markov kernel  $P$  and initial distribution  $\nu \in \mathbb{M}_1(X)$

## Lemma (The joint law)

For any  $n \in \mathbb{N}$ , the **joint law of  $X_{0:n}$**  is

$$\nu(dx_0) \prod_{i=1}^n P(x_{i-1}, dx_i)$$

(with the convention that  $\prod_{i=0}^{-1} = 1$ ). In particular, the law of  $X_n$  is  $\nu P^n$ .

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- 1 let  $P$  be a Markov kernel on  $X \times \mathcal{X}$
- 2 let  $\nu \in M_1(X)$

## Theorem

**(The canonical space)** Given (1) and (2), there exists a unique probability measure  $\mathbb{P}_\nu$  on the canonical space  $(X^{\mathbb{N}}, \mathcal{X}^{\otimes \mathbb{N}})$  such that

- under  $\mathbb{P}_\nu$ , the coordinate process  $\{X_n : n \in \mathbb{N}\}$  is a Markov chain with Markov kernel  $P$  and initial distribution  $\nu$ .

① We use the notation:  $\mathbb{P}_x = \mathbb{P}_{\delta_x}$ .

② For any  $A \in \mathcal{X}^{\otimes(n+1)}$

$$\mathbb{P}_\nu(X_{0:n} \in A) = \int_{\mathcal{X}} \nu(dx_0) \mathbb{P}_{x_0}(X_{0:n} \in A).$$

③ We can replace  $n$  by  $\infty$ : for all  $A \in \mathcal{X}^{\otimes \mathbb{N}}$ ,

$$\begin{aligned} \mathbb{P}_\nu(A) &= \mathbb{P}_\nu(X_{0:\infty} \in A) = \int_{\mathcal{X}} \nu(dx_0) \mathbb{P}_{x_0}(X_{0:\infty} \in A) \\ &= \int_{\mathcal{X}} \nu(dx_0) \mathbb{P}_{x_0}(A). \end{aligned}$$

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## Theorem

**(The Markov property)** For any  $\nu \in M_1(X)$ , any non-negative or bounded function  $h$  on  $X^{\mathbb{N}}$  and any  $k \in \mathbb{N}$ ,

$$\mathbb{E}_{\nu} [h(X_{k:\infty}) | \mathcal{F}_k] = \mathbb{E}_{X_k} [h(X_{0:\infty})], \quad \mathbb{P}_{\nu} - a.s. \quad (1)$$

where  $\mathcal{F}_k = \sigma(X_{0:k})$ .