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# Markov Chain Monte Carlo Theory and Practical applications

**Chapter 4**: Geometric ergodicity and CLT

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#### Theory and **Applications**

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Geometric ergodicity means that there exists constants C>0 and  $\varrho\in(0,1)$  such that for all  $n\in\mathbb{N}$ ,

$$\|\mu P^n - \pi\|_{\mathrm{TV}} \leqslant C\varrho^n$$

where  $\|\cdot\|_{\mathrm{TV}}$  is the total variation norm (to be defined later) between two measures.

- **1**  $\mu P^n$  is the law of  $X_n$  starting from  $X_0 \sim \mu$
- 2  $\pi$  is the law of  $X_n$  starting from  $X_0 \sim \pi$
- Geometric ergodicity for Markov chains should not be confused with the notion of ergodic dynamical systems

**CLT** means that

$$n^{-1/2} \sum_{k=0}^{n-1} \{h(X_k) - \pi(h)\} \stackrel{\mathcal{L}_{\mathbb{P}_{\pi}}}{\Rightarrow} \mathcal{N}(0, \sigma_{\pi}^2(h))$$

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Coupling and total variation

# Definition

Let  $(X, \mathcal{X})$  be a measurable space and let  $\nu, \mu$  be two probability measures on  $(X, \mathcal{X})$ . We define  $\mathcal{C}(\mu, \nu)$ , the coupling set associated to  $(\mu, \nu)$  as follows

$$\mathcal{C}(\mu,\nu) = \left\{ \gamma \in \mathsf{M}_1(\mathsf{X}^2) \, : \, \gamma(\cdot \times \mathsf{X}) = \mu(\cdot), \gamma(\mathsf{X} \times \cdot) = \nu(\cdot) \right\}$$

Any  $\gamma \in \mathcal{C}(\mu, \nu)$  is called a coupling of  $(\mu, \nu)$ .

- 1 In words,  $\gamma$  is a coupling of  $(\mu, \nu)$  if the following
- **Example:** The law of (X, X) where  $X \sim \mu$  is a coupling

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- **Example:** The law of (X,X) where  $X \sim \mu$  is a coupling

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- In words,  $\gamma$  is a coupling of  $(\mu, \nu)$  if the following property holds: if  $(X,Y) \sim \gamma$ , then we have the marginal conditions:  $X \sim \mu$  and  $Y \sim \nu$ .
- **Example:** The law of (X, X) where  $X \sim \mu$  is a coupling of  $(\mu, \mu)$ . Other example if  $X \sim \mu$  and  $Y \sim \mu$  and  $X \perp Y$ , then, the law of (X, Y) is a coupling of  $(\mu, \mu)$ .

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# Definition

Let  $(X, \mathcal{X})$  be a measurable space and let  $\nu, \mu$  be two probability measures  $\mu, \nu \in M_1(X)$ . Then the total variation norm between  $\mu$  and  $\nu$  noted  $\|\mu - \nu\|_{TV}$ , is defined by

$$\|\mu - \nu\|_{\text{TV}} = 2\sup\{|\mu(f) - \nu(f)| : f \in \mathsf{F}(\mathsf{X}), 0 \leqslant f \leqslant 1\}$$
(1)

$$= \int |\varphi_0 - \varphi_1|(x)\zeta(\mathrm{d}x)$$
 (2)  
=  $2\inf \{\mathbb{P}(X \neq Y) : (X,Y) \sim \gamma \text{ where } \gamma \in \mathcal{C}(\mu,\nu)\}$  (3)

where 
$$\mu(\mathrm{d}x) = \varphi_0(x)\zeta(\mathrm{d}x)$$
 and  $\nu(\mathrm{d}x) = \varphi_1(x)\zeta(\mathrm{d}x)$ .

Proof is given in the lecture notes

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# Assumption A1

[Minorizing condition] for all d>0, there exists  $\epsilon_d>0$  and a probability measure  $\nu_d$  such that

$$\forall x \in C_d := \{ V \leqslant d \}, \quad P(x, \cdot) \geqslant \epsilon_d \nu_d(\cdot)$$
 (4)

# Assumption A2

**Drift condition** there exists a constants  $(\lambda, b) \in (0, 1) \times \mathbb{R}^+$  such that for all  $x \in X$ .

$$PV(x) \leqslant \lambda V(x) + \delta$$

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#### Theorem

(Forgetting of the initialization) Assume (A1) and (A2) for some measurable function  $V \geqslant 1$ . Then, there exists a constant  $\varrho \in (0,1)$  such that for all  $x,x' \in X$  and all  $n \in \mathbb{N}$ ,

$$||P^n(x,\cdot) - P^n(x',\cdot)||_{\mathrm{TV}} \le \varrho^n \left[V(x) + V(x')\right].$$

Proof is hard. It is given in the lecture notes

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# Corollary

(Geometric ergodicity) Assume that (A1) and (A2) hold for some measurable function  $V \geqslant 1$ . Then, the Markov kernel P admits a unique invariant probability measure  $\pi$ . Moreover,  $\pi(V) < \infty$  and there exists constants  $(\varrho, \alpha) \in (0,1) \times \mathbb{R}^+$  such that for all  $\mu \in M_1(X)$  and all  $n \in \mathbb{N}$ ,

$$\|\mu P^n - \pi\|_{\mathrm{TV}} \leqslant \alpha \varrho^n \mu(V)$$

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Let  $(M_n)_{n\in\mathbb{N}}$  be a sequence of random variables on the same probability space  $(\Omega,\mathcal{F},\mathbb{P})$  and let  $(\mathcal{F}_n)_{n\in\mathbb{N}}$  be a filtration (ie for all  $n\in\mathbb{N}$ ,  $\mathcal{F}_n\subset\mathcal{F}_{n+1}\subset\mathcal{F}$ ).

# Definition

We say that  $(M_n)_{n\in\mathbb{N}}$  is a  $(\mathcal{F}_n)$ -martingale if for all  $n\in\mathbb{N}$ ,  $M_n$  is integrable and for all  $n\geqslant 1$ ,

$$\mathbb{E}[M_n|\mathcal{F}_{n-1}] = M_{n-1}$$

The increment process of the martingale is by definition  $(M_{n+1}-M_n)_{n\in\mathbb{N}}$ .

#### Theoren

If a sequence  $(M_n)_{n\in\mathbb{N}}$  is a  $(\mathcal{F}_n)$ -martingale with stationary and square integrable increments, then

$$n^{-1/2}M_n \stackrel{\mathcal{L}_{\mathbb{P}}}{\Rightarrow} \mathcal{N}\left(0, \mathbb{E}[(M_1 - M_0)^2]\right)$$

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# **Definition**

For a given measurable function h such that  $\pi |h| < \infty$ , the Poisson equation is defined by

$$\hat{h} - P\hat{h} = h - \pi(h) \tag{5}$$

A solution to the Poisson equation is a function  $\hat{h}$  for which (5) holds provided that  $P|\hat{h}|(x) < \infty$  for all  $x \in X$ .

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# Link between Poisson equations and Martingales

Define

$$S_n(h) = \sum_{k=0}^{n-1} \{h(X_k) - \pi(h)\}\$$
  
=  $M_n(\hat{h}) + \hat{h}(X_0) - \hat{h}(X_n)$ 

where

$$M_n(\hat{h}) = \sum_{k=1}^{n} \left\{ \hat{h}(X_k) - P\hat{h}(X_{k-1}) \right\}$$
 (6)

$$\mathbb{E}[M_n(\hat{h})|\mathcal{F}_{n-1}] - M_{n-1}(h) = \mathbb{E}[\hat{h}(X_n) - P\hat{h}(X_{n-1})|\mathcal{F}_{n-1}]$$
$$= P\hat{h}(X_{n-1}) - P\hat{h}(X_{n-1}) = 0$$

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# Theorem

Assume that (A1) and (A2) hold for some measurable function  $V \geqslant 1$ . Then, for any function h such that  $|h| \leqslant V$ , the function

$$\hat{h} = \sum_{n=0}^{\infty} \{ P^n h - \pi(h) \}$$
 (7)

is well-defined. Moreover,  $\hat{h}$  is a solution of the Poisson equation associated to h and there exists a constant  $\gamma$  such that for all  $x \in X$ .

$$|\hat{h}(x)| \leqslant \gamma V(x)$$

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#### Theorem

(CLT with Poisson assumption) Let P be a Markov kernel with a unique invariant probability measure  $\pi$ . Let  $h \in L^2(\pi)$ . Assume that there exists a solution  $\hat{h} \in L^2(\pi)$  to the Poisson equation  $\hat{h} - P\hat{h} = h$ . Then

$$n^{-1/2} \sum_{k=0}^{n-1} \{h(X_k) - \pi(h)\} \stackrel{\mathcal{L}_{\mathbb{R}_{\pi}}}{\Rightarrow} \mathcal{N}(0, \sigma_{\pi}^2(h))$$

where

$$\sigma_{\pi}^{2}(h) = \mathbb{E}_{\pi}[\{\hat{h}(X_{1}) - P\hat{h}(X_{0})\}^{2}]$$
(8)

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$$n^{-1/2} \sum_{k=0}^{n-1} \{h(X_k) - \pi(h)\} \stackrel{\mathcal{L}_{\mathbb{P}_{\pi}}}{\Rightarrow} \mathcal{N}(0, \sigma_{\pi}^2(h)),$$

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# Theorem

# (CLT with A1-A2 assumptions) Assume that (A1 and

(A2) hold for some function V. Then, for all measurable functions h such that  $|h|^2 \leqslant V$ ,

$$n^{-1/2} \sum_{k=0}^{n-1} \{h(X_k) - \pi(h)\} \stackrel{\mathcal{L}_{\mathbb{P}_{\pi}}}{\Rightarrow} \mathcal{N}(0, \sigma_{\pi}^2(h)) ,$$

where

$$\sigma_{\pi}^{2}(h) = \mathbb{E}_{\pi}[\{\hat{h}(X_{1}) - P\hat{h}(X_{0})\}^{2}]$$
(9)

and  $\hat{h}$  is defined as in (7).

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#### Theorem

(CLT with A1-A2 assumptions) Assume that (A1 and (A2) hold for some function V. Then, for all measurable functions h such that  $|h|^2 \leq V$ ,

$$n^{-1/2} \sum_{k=0}^{n-1} \{h(X_k) - \pi(h)\} \stackrel{\mathcal{L}_{\mathbb{P}_{\pi}}}{\Rightarrow} \mathcal{N}(0, \sigma_{\pi}^2(h)) ,$$

where

$$\sigma_{\pi}^{2}(h) = \mathbb{E}_{\pi}[\{\hat{h}(X_{1}) - P\hat{h}(X_{0})\}^{2}]$$
(9)

and  $\hat{h}$  is defined as in (7).